

# Tianyang Zhao

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<b>EDUCATION</b>	<b>University of California, Los Angeles</b> Ph.D. candidate in Statistics, GPA: 3.97/4.00 Sep 2019 – present Advisor: Prof. Ying Nian Wu, <i>Center for Vision, Cognition, Learning and Autonomy (VCLA)</i>
	<b>Peking University</b> B.S. in Data Science and Big Data Technology; <i>Yuanpei College</i> Sep 2015 – Jul 2019 Advisor: Prof. Yizhou Wang, <i>School of EECS</i>
<b>INTERESTS</b>	Machine Learning, Computer Vision, Language Models, Vision and Language, Autonomous Driving
<b>PUBLICATIONS</b>	<ol style="list-style-type: none"><li>[1] Tianyang Zhao, Yifei Xu, Mathew Monfort, Wongun Choi, Chris Baker, Yibiao Zhao, Yizhou Wang, Ying Nian Wu. “Multi-Agent Tensor Fusion for Contextual Trajectory Prediction”. <i>IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2019.</li><li>[2] Tianyang Zhao, Kunwar Yashraj Singh, Srikar Appalaraju, Peng Tang, Vijay Mahadevan, R. Manmatha, Ying Nian Wu. “No Head Left Behind - Multi-Head Alignment Distillation for Transformers”. Accepted by <i>AAAI Conference on Artificial Intelligence (AAAI)</i>, 2024.</li><li>[3] Bo Pang, Tianyang Zhao, Xu Xie, Ying Nian Wu. “Trajectory Prediction with Latent Belief Energy-Based Model”. <i>IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)</i>, 2021.</li><li>[4] Yifei Xu, Jianwen Xie, Tianyang Zhao, Chris Baker, Yibiao Zhao, Ying Nian Wu. “Energy-Based Continuous Inverse Optimal Control”. <i>IEEE Transactions on Neural Networks and Learning System (TNNLS)</i>, 2022;</li></ol>
<b>WORK EXPERIENCE</b>	<b>Amazon Inc, AWS AI Labs - Computer Vision Team</b> <i>Applied Scientist Intern   Mentors: Yash Singh, Srikar Appalaraju, Peng Tang</i> Sep 2023 – Mar 2024 <ul style="list-style-type: none"><li>• Researched knowledge distillation for large language models.</li></ul> <i>Applied Scientist Intern   Mentors: Yash Singh, Srikar Appalaraju</i> Jun 2022 – Sep 2022 <ul style="list-style-type: none"><li>• Researched knowledge distillation for large vision language Transformers to shorten their inference time on visual question answering (VQA) and image captioning tasks.</li><li>• Proposed and experimented a new attention map distillation method for multi-head Transformers.</li></ul> <b>Twitter Inc, Cortex - Applied Research Team</b> <i>Engineering Intern   Mentors: Ying Xiao, Yury Malkov, Ahmed El-Kishky</i> Jun 2021 – Sep 2021 <ul style="list-style-type: none"><li>• Applied deep language models on users’ historically engaged tweet sequences to build user profiles for future engagement prediction, and achieved offline gains over current production model.</li><li>• Explored efficiency optimizations for overcoming IO barriers in training these models on very large scale distributed dataset, including re-implementing product quantization decoder on GPU.</li><li>• Researched intermediate bottleneck representations for transformers to shorten inference time.</li></ul> <i>Software Engineering Intern   Mentor: Yury Malkov</i> Jun 2020 – Sep 2020 <ul style="list-style-type: none"><li>• Explored sparse attention networks on tabular data for ads recommendation system and achieved significant offline gains over current production model.</li></ul>
<b>SELECTED RESEARCH EXPERIENCE</b>	<b>UCLA, Center for Vision, Cognition, Learning and Autonomy</b> Mar 2020 – Present <ul style="list-style-type: none"><li>• Developed deep latent-space energy-based models (EBM) for unsupervised and generative learning, and developed an amortized variational inference version of it for trajectory prediction;</li><li>• Applied short-run Markov Chain Monte Carlo (MCMC) to reduce sampling time for the negative phase of training these energy-based models;</li><li>• Studied inhibition neurons for inducing sparsity and composition in deep representation learning;</li><li>• Explored semi-supervised learning with consistency regularization for learning with noisy samples.</li></ul> <b>ISEE Inc, Autonomous Driving - Behavior Prediction Team</b> Jun 2018 – Nov 2018

- Designed Multi-Agent Tensor Fusion ConvNets to reason about social interactions among varying numbers of agents & about constraints from scene contexts for trajectory prediction;
- Explored energy-based continuous Inverse Optimal Control (IOC) to learn non-Markovian cost functions over vehicle trajectories.

**PROFESSIONAL SERVICES**

**Peer-reviewed Conferences**

IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2021-2024  
 IEEE/CVF International Conference on Computer Vision (ICCV), 2021, 2023  
 Association for Computational Linguistics Rolling Review (ACL), 2024  
 IEEE International Conference on Robotics and Automation (ICRA), 2022  
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020

**Peer-reviewed Journals**

IEEE Robotics and Automation Letters (RA-L)  
 IEEE Transactions on Mobile Computing (TMC)  
 Pattern Recognition (PR)  
 IEEE Transactions on Intelligent Transportation Systems (TITS)

**TEACHING EXPERIENCE**

**Teaching Assistant** | *Department of Statistics, UCLA*

Introduction to Probability (Stats 100A, for undergraduate students)  
 Theoretical Statistics (Stats 200B, for PhD and MS students)

Sep 2020- Dec 2020  
 Jan 2021- Mar 2021

**AWARDS AND HONORS**

Merit Student (top 10%), Peking University  
 Meritorious Winner (top 15%), Mathematical Contest in Modeling (MCM)  
 3rd Prize, ACM Programming Contest in Peking University

Nov 2017  
 Feb 2018  
 May 2017